

## Chapters 1-2-4: Ordinary Differential Equations

Sections 1.1, 1.7, 2.2, 2.6, 2.7, 4.2 & 4.3

## 1. Ordinary differential equations

- An **ordinary differential equation** of order  $n$  is an equation of the form

$$\frac{d^n y}{dx^n} = f\left(x, y, \frac{dy}{dx}, \dots, \frac{d^{n-1}y}{dx^{n-1}}\right). \quad (1)$$

- A **solution** to this differential equation is an  $n$ -times differentiable function  $y(x)$  which satisfies (1).

- Example:** Consider the differential equation

$$y'' - 2y' + y = 0.$$

- What is the order of this equation?
- Are  $y_1(x) = e^x$  and  $y_2(x) = x e^x$  solutions of this differential equation?
- Are  $y_1(x)$  and  $y_2(x)$  linearly independent?

## Initial and boundary conditions

- An **initial condition** is the prescription of the values of  $y$  and of its  $(n - 1)$ st derivatives at a point  $x_0$ ,

$$y(x_0) = y_0, \quad \frac{dy}{dx}(x_0) = y_1, \dots, \frac{d^{n-1}y}{dx^{n-1}}(x_0) = y_{n-1}, \quad (2)$$

where  $y_0, y_1, \dots, y_{n-1}$  are given numbers.

- Boundary conditions** prescribe the values of linear combinations of  $y$  and its derivatives for two different values of  $x$ .
- In **MATH 254**, you saw various methods to solve ordinary differential equations. Recall that initial or boundary conditions should be imposed **after** the general solution of a differential equation has been found.

## 2. Existence and uniqueness of solutions

- Equation (1) may be written as a **first-order system**

$$\frac{dY}{dx} = F(x, Y) \quad (3)$$

by setting  $Y = \left[ y, \frac{dy}{dx}, \frac{d^2y}{dx^2}, \dots, \frac{d^{n-1}y}{dx^{n-1}} \right]^T$ .

- Existence and uniqueness of solutions:** if  $F$  in (3) is continuously differentiable in the rectangle

$$R = \{(x, Y), |x - x_0| < a, \|Y - Y_0\| < b, a, b > 0\},$$

then the initial value problem

$$\frac{dY}{dx} = F(x, Y), \quad Y(x_0) = Y_0,$$

has a solution in a neighborhood of  $(x_0, Y_0)$ . Moreover, this solution is unique.

## Existence and uniqueness of solutions (continued)

- **Examples:**

- Does the initial value problem

$$y'' - 2y' + y = 0, \quad y(0) = 1, \quad y'(0) = 0$$

have a solution near  $x = 0$ ,  $y = 1$ ,  $y' = 0$ ? If so, is it unique?

- Does the initial value problem

$$y' = \sqrt{y}, \quad y(0) = y_0$$

have a unique solution for all values of  $y_0$ ?

- Does the initial value problem

$$y' = y^2, \quad y(1) = 1$$

have a solution near  $x = 1$ ,  $y = 1$ ? Does this solution exist for all values of  $x$ ?

## Existence and uniqueness for linear systems

- Consider a **linear system** of the form

$$\frac{dY}{dx} = A(x)Y + B(x),$$

where  $Y$  and  $B(x)$  are  $n \times 1$  column vectors, and  $A(x)$  is an  $n \times n$  matrix whose entries may depend on  $x$ .

- **Existence and uniqueness of solutions:** If the entries of the matrix  $A(x)$  and of the vector  $B(x)$  are continuous on some open interval  $I$  containing  $x_0$ , then the initial value problem

$$\frac{dY}{dx} = A(x)Y + B(x), \quad Y(x_0) = Y_0$$

has a unique solution on  $I$ .

## Existence and uniqueness for linear systems (continued)

- **Examples:**

- Apply the above theorem to the initial value problem

$$y'' - 2y' + y = 3x, \quad y(0) = 1, \quad y'(0) = 0$$

- Does the initial value problem

$$y^{(4)} - x^3 y'' + 3y = 0, \\ y(0) = 1, \quad y'(0) = 1, \quad y''(0) = 0, \quad y^{(3)}(0) = 0$$

have a unique solution on the interval  $[-1, 1]$ ?

## 3. Linear differential equations and systems

- The general solution of a homogeneous linear equation of order  $n$  is a **linear combination** of  $n$  **linearly independent** solutions.
- As a consequence, if we have a method to find  $n$  linearly independent solutions, then we know the general solution.
- In **MATH 254**, you saw methods to find linearly independent solutions of homogeneous linear ordinary differential equations **with constant coefficients**.
- This includes **linear equations** of the form  $ay'' + by' + cy = 0$ , and **linear systems** of the form  $\frac{dY}{dx} = AY$ , where  $A$  is an  $n \times n$  constant matrix and  $Y(x)$  is a column vector in  $\mathbb{R}^n$ .

## Linear differential equations and systems (continued)

- A set  $\{y_1(x), y_2(x), \dots, y_n(x)\}$  of  $n$  functions is **linearly independent** if its **Wronskian is different from zero**.
- Similarly, a set of  $n$  vectors  $\{Y_1(x), Y_2(x), \dots, Y_n(x)\}$  in  $\mathbb{R}^n$  is **linearly independent** if its **Wronskian is different from zero**.
- The Wronskian of  $n$  functions  $y_1(x), y_2(x), \dots, y_n(x)$  is given by

$$W(y_1, y_2, \dots, y_n) = \begin{vmatrix} y_1 & y_2 & \cdots & y_n \\ y_1' & y_2' & \cdots & y_n' \\ y_1'' & y_2'' & \cdots & y_n'' \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(n-1)} & y_2^{(n-1)} & \cdots & y_n^{(n-1)} \end{vmatrix}$$

## Linear differential equations and systems (continued)

- The **Wronskian** of  $n$  vectors  $Y_1(x), Y_2(x), \dots, Y_n(x)$  in  $\mathbb{R}^n$  is given by

$$W(Y_1, Y_2, \dots, Y_n) = \det([Y_1 \ Y_2 \ \cdots \ Y_n]),$$

where  $[Y_1 \ Y_2 \ \cdots \ Y_n]$  denotes the  $n \times n$  matrix whose columns are  $Y_1(x), Y_2(x), \dots, Y_n(x)$ .

- **Finding  $n$  linearly independent solutions** to a homogeneous linear differential equation or system of order  $n$ , **is equivalent to finding a basis** for the set of solutions.
- The next two slides summarize how to find linearly independent solutions in two particular cases.

## Homogeneous linear equations with constant coefficients

To find the general solution to an ordinary differential equation of the form  $ay'' + by' + cy = 0$ , where  $a, b, c \in \mathbb{R}$ , proceed as follows.

- 1 Find the characteristic equation,  $a\lambda^2 + b\lambda + c = 0$  and solve for the roots  $\lambda_1$  and  $\lambda_2$ .
- 2 If  $b^2 - 4ac > 0$ , then the two roots are real and the general solution is  $y = C_1 e^{\lambda_1 x} + C_2 e^{\lambda_2 x}$ .
- 3 If  $b^2 - 4ac < 0$  the two roots are complex conjugate of one another and the general solution is of the form  $y = e^{\alpha x} (C_1 \cos(\beta x) + C_2 \sin(\beta x))$ , where  $\alpha = \Re e(\lambda_1) = \frac{-b}{2a}$ , and  $\beta = \Im m(\lambda_1) = \frac{\sqrt{4ac - b^2}}{2a}$ .
- 4 If  $b^2 - 4ac = 0$ , then there is a double root  $\lambda = -\frac{b}{2a}$ , and the general solution is  $y = (C_1 + C_2 x) e^{\lambda x}$ .

## Homogeneous linear systems with constant coefficients

To find the general solution of the linear system  $\frac{dY}{dx} = AY$ , where  $A$  is an  $n \times n$  matrix with constant coefficients, proceed as follows.

- 1 Find the eigenvalues and eigenvectors of  $A$ .
- 2 If the matrix has  **$n$  linearly independent eigenvectors**  $U_1, U_2, \dots, U_n$ , associated with the eigenvalues  $\lambda_1, \lambda_2, \dots, \lambda_n$ , then the general solution is  $Y = C_1 U_1 e^{\lambda_1 x} + C_2 U_2 e^{\lambda_2 x} + \cdots + C_n U_n e^{\lambda_n x}$ , where the eigenvalues  $\lambda_i$  may not be distinct from one another, and the  $C_i$ 's,  $\lambda_i$ 's and  $U_i$ 's **may be complex**.

If  $A$  has real coefficients, then the eigenvalues of  $A$  are either real or come in complex conjugate pairs. If  $\lambda_i = \overline{\lambda_j}$ , then the corresponding eigenvectors  $U_i$  and  $U_j$  are also complex conjugate of one another.

## 4. Nonhomogeneous linear equations and systems

- The general solution  $y$  to a **non-homogeneous linear equation** of order  $n$  is of the form

$$y(x) = y_h(x) + y_p(x),$$

where  $y_h(x)$  is the **general solution to the corresponding homogeneous equation** and  $y_p(x)$  is a **particular solution** to the non-homogeneous equation.

- Similarly, the general solution  $Y$  to a linear system of equations  $\frac{dY}{dx} = A(x)Y + B(x)$  is of the form

$$Y(x) = Y_h(x) + Y_p(x),$$

where  $Y_h(x)$  is the **general solution to the homogeneous system**  $\frac{dY}{dx} = A(x)Y$  and  $Y_p(x)$  is a **particular solution** to the non-homogeneous system.

## Nonhomogeneous linear equations and systems (continued)

- In **MATH 254**, you saw methods to find particular solutions to non-homogeneous linear equations and systems of equations.
- You should **review these methods** and make sure you know how to apply them.