

# Chapter 6: Laplace Transforms

# 1. Definitions

- The **Laplace transform**,  $\mathcal{L}(f)$ , of a piecewise continuous function  $f$  (defined on  $[0, \infty)$ ) is given by

$$\mathcal{L}(f)(s) = F(s) = \int_0^{\infty} \exp(-s t) f(t) dt.$$

- Clearly, the above integral only converges if  **$f$  does not grow too fast at infinity**. More precisely, if there exist constants  $M > 0$  and  $k \in \mathbb{R}$  such that

$$|f(t)| \leq M \exp(k t)$$

for  $t$  large enough, then the Laplace transform of  $f$  exists for all  $s > k$ .

- If  $f$  has a Laplace transform  $F$ , we also say that  $f$  is the **inverse Laplace transform** of  $F$ , and write  $f = \mathcal{L}^{-1}(F)$ .

## 2. Properties of the Laplace transform

- The Laplace transform is a **linear transformation**, i.e. if  $f_1$  and  $f_2$  have Laplace transforms, and if  $\alpha_1$  and  $\alpha_2$  are constants, then

$$\mathcal{L}(\alpha_1 f_1 + \alpha_2 f_2) = \alpha_1 \mathcal{L}(f_1) + \alpha_2 \mathcal{L}(f_2).$$

- As for Fourier transforms, the statement

$$f = \mathcal{L}^{-1}(\mathcal{L}(f))$$

should be understood in a point-wise fashion only **at points where  $f$  is continuous**.

- Since **there is no explicit formula for the inverse Laplace transform**, formal inversion is accomplished by using tables, shifting  $t$  and  $s$ , taking derivatives of known Laplace transforms, or integrating them.

# s-shifting, Laplace transform of derivatives & antiderivatives

- **Note:** All of the formulas written in what follows implicitly assume that the various functions used have well-defined Laplace transforms. One should therefore **check that the corresponding Laplace transforms exist** before using these formulas.

- **s-shifting formulas**

$$\mathcal{L}(e^{at}f(t))(s) = F(s-a), \quad e^{at}f(t) = \mathcal{L}^{-1}(F(s-a))(t).$$

- **Laplace transform of derivatives**

$$\begin{aligned}\mathcal{L}(f')(s) &= s\mathcal{L}(f)(s) - f(0), \\ \mathcal{L}(f'')(s) &= s^2\mathcal{L}(f)(s) - sf(0) - f'(0).\end{aligned}$$

# Laplace transform of derivatives and antiderivatives

- More generally,

$$\mathcal{L}\left(f^{(n)}\right)(s) = s^n \mathcal{L}(f)(s) - s^{n-1} f(0) - s^{n-2} f'(0) - \dots - f^{(n-1)}(0).$$

- Laplace transform of antiderivatives

$$\mathcal{L}\left(\int_0^t f(\tau) d\tau\right)(s) = \frac{1}{s} \mathcal{L}(f)(s),$$
$$\int_0^t f(\tau) d\tau = \mathcal{L}^{-1}\left(\frac{1}{s} \mathcal{L}(f)(s)\right)(t).$$

- **Examples:**

- Find the Laplace transforms of  $\sin(\omega t)$  and  $\cos(\omega t)$ .
- Find the inverse Laplace transforms of  $1/(s(s^2 + 1))$  and  $1/(s^2(s^2 + 1))$ .

# Heaviside and delta functions; $t$ -shifting

- The **Heaviside function** (or **step function**)  $H(t)$  is defined as

$$H(t) = \begin{cases} 0 & \text{if } t < 0 \\ 1 & \text{if } t \geq 0 \end{cases} .$$

- We can calculate that, for  $a > 0$ ,  $\mathcal{L}(H(t - a))(s) = \frac{e^{-as}}{s}$ .
- More generally, we have the following **time-shifting formulas** for  $a > 0$ .

$$\begin{aligned} \mathcal{L}(f(t - a)H(t - a))(s) &= e^{-as}\mathcal{L}(f)(s) \\ f(t - a)H(t - a) &= \mathcal{L}^{-1}(e^{-as}\mathcal{L}(f)(s))(t). \end{aligned}$$

- The above formulas are useful to calculate the Laplace transforms of signals that are defined in a **piecewise fashion**.

# Delta functions

- The **Dirac delta function** (or distribution) is defined as the limit of the following sequence of narrow top-hat functions,

$$\delta(t) = \lim_{\epsilon \rightarrow 0} f_{\epsilon}(t), \quad f_{\epsilon}(t) = \begin{cases} \frac{1}{2\epsilon} & \text{if } |t| \leq \epsilon \\ 0 & \text{otherwise} \end{cases} .$$

- Since  $\int_{-\infty}^{\infty} f_{\epsilon}(t) dt = 1$ , we also write that  $\int_{-\infty}^{\infty} \delta(t) dt = 1$ .
- More generally, for a “well-behaved” function  $g$ , we have 
$$\int_{-\infty}^{\infty} g(t) \delta(t - a) dt = g(a).$$
- For  $a > 0$ , this allows us to define the **Laplace transform of  $\delta(t - a)$**  as

$$\mathcal{L}(\delta(t - a))(s) = e^{-as}.$$

# Differentiation and integration of Laplace transforms

In what follows, we write  $\mathcal{L}(f)(s)$  as  $F(s)$ .

- Differentiation of Laplace transforms

$$\mathcal{L}(t f(t))(s) = -F'(s), \quad \mathcal{L}^{-1}(F'(s))(t) = -t f(t).$$

- Integration of Laplace transforms

$$\mathcal{L}\left(\frac{f(t)}{t}\right)(s) = \int_s^\infty F(\nu) d\nu,$$
$$\mathcal{L}^{-1}\left(\int_s^\infty F(\nu) d\nu\right)(t) = \frac{f(t)}{t}.$$

- **Example:** Find the inverse Laplace transform of  $s/(s^2 + 1)^2$ .



# Applications to ODEs and systems of ODEs

- Solve  $y'' + y = t/\pi$ , with  $y(\pi) = 0$  and  $y'(\pi) = 1 + 1/\pi$ .
- Let  $f(t) = \begin{cases} \frac{1}{2\epsilon} & \text{if } 1 - \epsilon \leq t \leq 1 + \epsilon \\ 0 & \text{otherwise} \end{cases}$ , where  $\epsilon < 1$ . Solve  $y'' + 4y' - 5y = f(t)$  with initial conditions  $y(0) = 0$  and  $y'(0) = 0$ .
- Solve  $y'' + 4y' - 5y = \delta(t - 1)$ , with initial conditions  $y(0) = 0$ ,  $y'(0) = 0$ .
- Solve the initial value problem  $\frac{dX}{dt} = AX$ ,

$$A = \begin{bmatrix} -13 & -36 \\ 6 & 17 \end{bmatrix}, \quad X(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$