

Gradient bounds for Wachspress coordinates on polytopes

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Anatomy of a finite element error estimate

Goal: Approximate an unknown function $u : P \rightarrow \mathbb{R}$ where P is a polygon in \mathbb{R}^2 .

Approach: Use barycentric coordinates $\{\phi_{\mathbf{v}}\}$ associated to vertices $\{\mathbf{v}\}$ of P .

An error estimate can then be derived:

$$\underbrace{\left\| u - \sum_{\mathbf{v}} u(\mathbf{v})\phi_{\mathbf{v}} \right\|_{H^1(P)}}_{\substack{\text{approximation error} \\ \text{in value and derivative}}} \leq \underbrace{C_{\text{proj-}\phi} C_{\text{proj-linear}} \text{diam}(P)}_{\text{constants}} \underbrace{|u|_{H^2(P)}}_{\substack{\text{2nd order} \\ \text{oscillation} \\ \text{in } u}}$$

$C_{\text{proj-}\phi} \approx$ operator norm of projection $u \mapsto \sum_{\mathbf{v}} u(\mathbf{v})\phi_{\mathbf{v}}$

$C_{\text{proj-linear}} \approx$ operator norm of projection $u \mapsto$ linear polynomials on P

$\text{diam}(P) =$ diameter of polygon P .

Key question for polygonal finite element methods

What geometrical properties of P can cause $C_{\text{proj-}\phi}$ to be large?

Mathematical characterization

Problem statement

Given a simple convex d -dimensional polytope P , define

$$\Lambda := \sup_{\mathbf{x} \in P} \sum_{\mathbf{v} \in V} |\nabla \phi_{\mathbf{v}}(\mathbf{x})|$$

where $\phi_{\mathbf{v}}$ are **generalized barycentric coordinates** on P .

Find upper and lower bounds on Λ in terms of geometrical properties of P .

Remark: It can be shown that

$$C_{proj-\phi} = 1 + C_S(1 + \Lambda)$$

where C_S is the Sobolev embedding constant satisfying $\|u\|_{C^0(\bar{P})} \leq C_S \|u\|_{H^k(P)}$ independent of $u \in H^k(P)$, provided that $k > d/2$.

Hence, bounds on Λ help us characterize when $C_{proj-\phi}$ is large.

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The generalized barycentric coordinate approach

Let P be a convex polytope with vertex set V . We say that

$\phi_{\mathbf{v}} : P \rightarrow \mathbb{R}$ are **generalized barycentric coordinates (GBCs)** on P

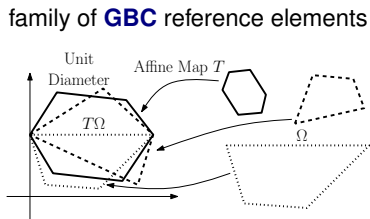
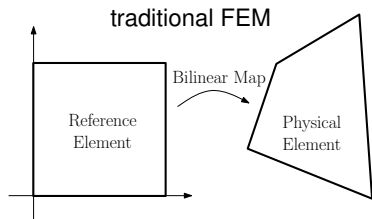
if they satisfy $\phi_{\mathbf{v}} \geq 0$ on P and $L = \sum_{\mathbf{v} \in V} L(\mathbf{v}_{\mathbf{v}}) \phi_{\mathbf{v}}$, $\forall L : P \rightarrow \mathbb{R}$ linear.

Familiar properties are implied by this definition:

$$\underbrace{\sum_{\mathbf{v} \in V} \phi_{\mathbf{v}} \equiv 1}_{\text{partition of unity}}$$

$$\underbrace{\sum_{\mathbf{v} \in V} \mathbf{v} \phi_{\mathbf{v}}(\mathbf{x}) = \mathbf{x}}_{\text{linear precision}}$$

$$\underbrace{\phi_{\mathbf{v}_i}(\mathbf{v}_j) = \delta_{ij}}_{\text{interpolation}}$$



The triangular case

$$\Lambda := \sup_{\mathbf{x} \in P} \sum_{\mathbf{v} \in V} |\nabla \phi_{\mathbf{v}}(\mathbf{x})|$$

If P is a triangle, Λ can be large when P has a large interior angle.

→ This is often called the **maximum angle condition** for finite elements.

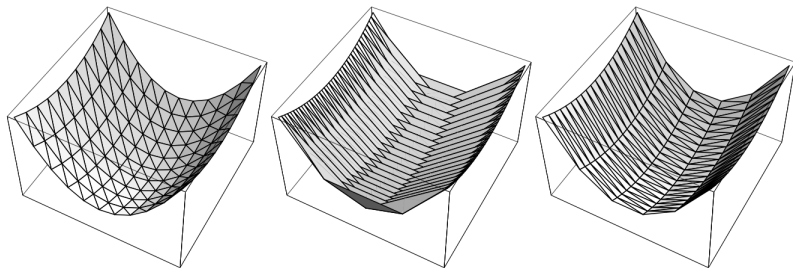
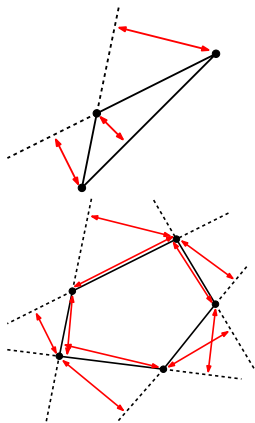


Figure from: [SHEWCHUK](#) *What is a good linear element?* Int'l Meshing Roundtable, 2002.

[BABUŠKA, AZIZ](#) *On the angle condition in the finite element method*, SIAM J. Num. An., 1976.

[JAMET](#) *Estimations d'erreur pour des éléments finis droits presque dégénérés*, ESAIM:M2AN, 1976.

Motivation



Observe that on triangles of fixed diameter:

$$\begin{aligned} |\nabla \phi_{\mathbf{v}}| \text{ large} &\iff \text{interior angle at } \mathbf{v} \text{ is large} \\ &\iff \text{the altitude "at } \mathbf{v}\text{" is small} \end{aligned}$$

For Wachspress coordinates, we generalize to polygons:

$$|\nabla \phi_{\mathbf{v}}| \text{ large} \iff \text{the "altitude" at } \mathbf{v} \text{ is small}$$

and then to **simple** polytopes.

*A **simple** d -dimensional polytope has exactly d faces at each vertex.*

Given a simple convex d -dimensional polytope P , let

h_* := minimum distance from a vertex to a hyper-plane of a non-incident face.

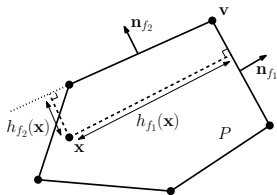
$$\text{Then } \sup_{\mathbf{x} \in P} \sum_{\mathbf{v} \in V} |\nabla \phi_{\mathbf{v}}(\mathbf{x})| =: \Lambda \text{ is large} \iff h_* \text{ is small}$$

Upper bound for simple convex polytopes

Theorem [Floater, G., Sukumar, 2014]

Let P be a simple convex polytope in \mathbb{R}^d and let $\phi_{\mathbf{v}}$ be **generalized Wachspress coordinates**.

Then $\Lambda \leq \frac{2d}{h_*}$ where $h_* = \min_f \min_{\mathbf{v} \notin f} \text{dist}(\mathbf{v}, f)$



$$\mathbf{p}_f(\mathbf{x}) := \frac{\mathbf{n}_f}{h_f(\mathbf{x})} = \begin{array}{l} \text{normal to face } f, \\ \text{scaled by the reciprocal} \\ \text{of the distance from } \mathbf{x} \text{ to } f \end{array}$$

$$\begin{aligned} w_{\mathbf{v}}(\mathbf{x}) &:= \det(\mathbf{p}_{f_1}(\mathbf{x}), \dots, \mathbf{p}_{f_d}(\mathbf{x})) \\ &= \text{volume formed by the } d \text{ vectors } \{\mathbf{p}_{f_i}(\mathbf{x})\} \\ &\quad \text{for the } d \text{ faces incident to } \mathbf{v} \end{aligned}$$

The **generalized Wachspress coordinates** are defined by $\phi_{\mathbf{v}}(\mathbf{x}) := \frac{w_{\mathbf{v}}(\mathbf{x})}{\sum_{\mathbf{u}} w_{\mathbf{u}}(\mathbf{x})}$

WACHSPRESS, *A Rational Finite Element Basis*, 1975.

JU, SCHAEFER, WARREN, DESBRUN, *A geometric construction of coordinates for convex polyhedra using polar duals* in *Geometry Processing 2005*, Eurographics, 2005.

Proof sketch for upper bound

To prove: $\sup_{\mathbf{x}} \sum_{\mathbf{v}} |\nabla \phi_{\mathbf{v}}(\mathbf{x})| =: \Lambda \leq \frac{2d}{h_*}$ where $h_* := \min_f \min_{\mathbf{v} \notin f} h_f(\mathbf{v})$.

- 1 Bound $|\nabla \phi_{\mathbf{v}}|$ by summations over faces incident and not incident to \mathbf{v} .

$$|\nabla \phi_{\mathbf{v}}| \leq \phi_{\mathbf{v}} \sum_{f \in F_{\mathbf{v}}} \frac{1}{h_f} \left(1 - \sum_{\mathbf{u} \in f} \phi_{\mathbf{u}} \right) + \phi_{\mathbf{v}} \sum_{f \notin F_{\mathbf{v}}} \frac{1}{h_f} \left(\sum_{\mathbf{u} \in f} \phi_{\mathbf{u}} \right)$$

- 2 Summing over \mathbf{v} gives a constant bound.

$$\sum_{\mathbf{v}} |\nabla \phi_{\mathbf{v}}| \leq 2 \sum_{f \in F} \frac{1}{h_f} \left(1 - \sum_{\mathbf{u} \in f} \phi_{\mathbf{u}} \right) \left(\sum_{\mathbf{u} \in f} \phi_{\mathbf{u}} \right)$$

- 3 Write $h_f(\mathbf{x})$ using $\phi_{\mathbf{v}}$ (possible since h_f is linear) and derive the bound.

$$\Lambda \leq 2 \sum_{f \in F} \left(\sum_{\mathbf{u} \in f} \phi_{\mathbf{u}} \right) \frac{1}{h_*} = 2 \sum_{\mathbf{v} \in V} |\{f : f \ni \mathbf{v}\}| \phi_{\mathbf{v}} \frac{1}{h_*} = \frac{2d}{h_*}$$

Lower bound for polytopes

Theorem [Floater, G., Sukumar, 2014]

Let P be a simple convex polytope in \mathbb{R}^d and let $\phi_{\mathbf{v}}$ be **any** generalized barycentric coordinates on P . Then

$$\frac{1}{h_*} \leq \Lambda$$

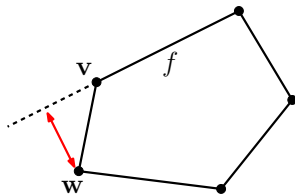
Proof sketch:

- 1 Show that $h_* = h_f(\mathbf{w})$, for some particular face f of P and vertex $\mathbf{w} \notin f$.
- 2 Let \mathbf{v} be the vertex in f closest to \mathbf{w} . Show that

$$|\nabla \phi_{\mathbf{w}}(\mathbf{v})| = \frac{1}{h_f(\mathbf{w})}$$

- 3 Conclude the result, since

$$\Lambda \geq |\nabla \phi_{\mathbf{w}}(\mathbf{v})| = \frac{1}{h_f(\mathbf{w})} = \frac{1}{h_*}$$



- 1 Upper and lower bounds for simple convex polytopes
- 2 Summary of results and special cases**
- 3 Matlab code and numerical experiments

Upper and lower bounds on polytopes

For a polytope $P \subset \mathbb{R}^d$, define $\Lambda := \sup_{\mathbf{x} \in P} \sum_{\mathbf{v}} |\nabla \phi_{\mathbf{v}}(\mathbf{x})|$.

simple convex polytope in \mathbb{R}^d	$\frac{1}{h_*}$	\leq	Λ	\leq	$\frac{2d}{h_*}$
d -simplex in \mathbb{R}^d	$\frac{1}{h_*}$	\leq	Λ	\leq	$\frac{d+1}{h_*}$
hyper-rectangle in \mathbb{R}^d	$\frac{1}{h_*}$	\leq	Λ	\leq	$\frac{d + \sqrt{d}}{h_*}$
regular k -gon in \mathbb{R}^2	$\frac{2(1 + \cos(\pi/k))}{h_*}$	\leq	Λ	\leq	$\frac{4}{h_*}$

Note that $\lim_{k \rightarrow \infty} 2(1 + \cos(\pi/k)) = 4$, so the bound is **sharp** in \mathbb{R}^2 .

FLOATER, G, SUKUMAR *Gradient bounds for Wachspress coordinates on polytopes*,
SIAM J. Numerical Analysis, 2014.

Relation to previous results

Prior work proved an upper bound on $|\nabla\phi_{\mathbf{v}}|$ for Wachspress coordinates on polygons:

$$|\nabla\phi_{\mathbf{v}}| \leq \frac{\pi^2}{2} \left(\frac{4}{(d_*)^4 \sin(\beta_*/2) \cos(\beta^*/2) \sin\beta^*} \right)^{2\beta^*/(\pi-\beta^*)}$$

where interior angles lie in $[\beta_*, \beta^*] \subset (0, \pi)$ and edges have length $\geq d_*$.

From this work, we have the simpler bound:

$$|\nabla\phi_{\mathbf{v}}| \leq \frac{4}{d_*(\sin\beta_*)(\sin\beta^*)}$$

A future project is to simplify existing bounds for the mean value coordinates.

G, RAND, BAJAJ *Error Estimates for Generalized Barycentric Interpolation*
Advances in Computational Mathematics, 37:3, 417-439, 2012

RAND, G, BAJAJ *Interpolation Error Estimates for Mean Value Coordinates*,
Advances in Computational Mathematics, 39:2, 327-347, 2013.

Outline

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Matlab code for Wachspress coordinates on polygons

Input: The vertices v_1, \dots, v_n of a polygon and a point x

Output: Wachspress functions ϕ_i and their gradients $\nabla\phi_i$

```
function [phi dphi] = wachspress2d(v,x)
n = size(v,1);
w = zeros(n,1);
R = zeros(n,2);
phi = zeros(n,1);
dphi = zeros(n,2);

un = getNormals(v); % computes the outward unit normal to each edge

p = zeros(n,2);
for i = 1:n
    h = dot(v(i,:) - x, un(i,:));
    p(i,:) = un(i,:) / h;
end

for i = 1:n
    im1 = mod(i-2,n) + 1;
    w(i) = det([p(im1,:);p(i,:)]);
    R(i,:) = p(im1,:) + p(i,:);
end

wsum = sum(w);
phi = w/wsum;

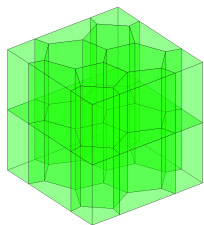
phiR = phi' * R;
for k = 1:2
    dphi(:,k) = phi .* (R(:,k) - phiR(:,k));
end
```

Matlab code for polygons and polyhedra

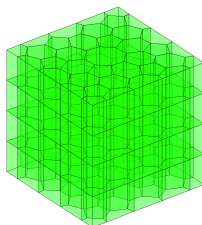
(simple or non-simple) included in appendix of

FLOATER, G, SUKUMAR *Gradient bounds for Wachspress coordinates on polytopes*, SIAM J. Numerical Analysis, 2014.

Numerical results



$h = 0.7071$



$h = 0.3955$

→ We fix a sequence of polyhedral meshes where h denotes the maximum diameter of a mesh element.

→ $\exists \gamma > 0$ such that if any element from any mesh in the sequence is scaled to have diameter 1, the computed value of h_* will be $\geq \gamma$.

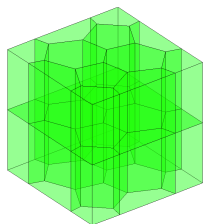
→ We solve the weak form of the Poisson problem:

$$\int_{\Omega} \nabla u \cdot \nabla w \, d\mathbf{x} = \int_{\Omega} f w \, d\mathbf{x}, \quad \forall w \in H_0^1(\Omega),$$

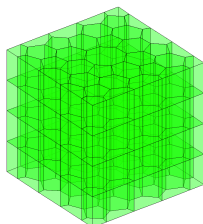
where $f(\mathbf{x})$ is defined so that the exact solution is $u(\mathbf{x}) = xyz(1-x)(1-y)(1-z)$.

→ Using Wachspress coordinates $\phi_{\mathbf{v}}$, the local stiffness matrix has entries of the form $\int_P \nabla \phi_{\mathbf{v}} \cdot \nabla \phi_{\mathbf{w}} \, d\mathbf{x}$, which we integrate by tetrahedralizing P and using a second-order accurate quadrature rule (4 points per tetrahedron).

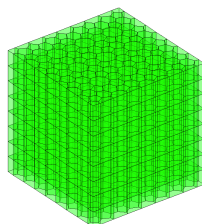
Numerical results



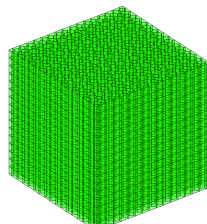
$h = 0.7071$



$h = 0.3955$



$h = 0.1977$



$h = 0.0989$

As expected, we observe optimal convergence convergence rates: quadratic in L^2 norm and linear in H^1 semi-norm.

Mesh	# of nodes	h	$\frac{\ u - u^h\ _{0,P}}{\ u\ _{0,P}}$	Rate	$\frac{ u - u^h _{1,P}}{ u _{1,P}}$	Rate
a	78	0.7071	2.0×10^{-1}	–	4.1×10^{-1}	–
b	380	0.3955	5.4×10^{-2}	2.28	2.1×10^{-1}	1.14
c	2340	0.1977	1.4×10^{-2}	1.96	1.1×10^{-1}	0.97
d	16388	0.0989	3.5×10^{-3}	1.99	5.4×10^{-2}	0.99
e	122628	0.0494	8.8×10^{-4}	2.00	2.7×10^{-2}	0.99

Acknowledgments



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Thanks for the invitation to speak!

Slides and pre-prints: <http://math.arizona.edu/~agillette/>

More on GBCs: <http://www.inf.usi.ch/hormann/barycentric>