

Perelman entropy and κ -noncollapse

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1 Gradient flow

Formulating an equation as a gradient flow has many advantages. Consider the heat equation

$$\frac{\partial f}{\partial t} = \Delta f$$

on a compact Riemannian manifold. It is easy to see that if one considers the energy

$$E(f) = \frac{1}{2} \int_M |\nabla f|_g^2 dV,$$

that if we take the time derivative of the energy when f satisfies the heat equation, we get

$$\begin{aligned} \frac{dE}{dt}(f) &= \int_M \nabla f \cdot \nabla \left(\frac{\partial f}{\partial t} \right) dV \\ &= - \int_M \Delta f \left(\frac{\partial f}{\partial t} \right) dV \\ &= - \int_M (\Delta f)^2 dV \leq 0. \end{aligned}$$

Thus we immediately get that the energy is decreasing and that stationary points are harmonic functions, i.e., functions which satisfy $\Delta f = 0$. This monotonicity also tells us that f cannot have periodic solutions which are not fixed points, for if $f(t_1, x) = f(t_2, x)$ for all x , then $E(f(t_1, \cdot)) = E(f(t_2, \cdot))$, and the monotonicity implies that $\Delta f = 0$ for $t \in [t_1, t_2]$.

The monotonicity is true in general for a gradient flow. If one has an energy $E(f)$, one defines the gradient flow as

$$\frac{\partial f}{\partial t} = \pm \text{grad}(E),$$

where the gradient vector $\text{grad}(E)$ is given so that

$$dE(X) = g(X, \text{grad}(E)),$$

for some metric g on the space of functions. In our case that g is the L^2 metric (which uses the Riemannian metric g on M).

It would be nice to represent Ricci flow in this way. It is not at all trivial to do this.

2 Ricci flow as a gradient flow

An obvious choice of functional is the Einstein-Hilbert functional:

$$EH(g) = \int_M R dV.$$

To calculate its variation, recall that if we have a variation of the metric $(\delta g)_{ij} = h_{ij}$, then we get

$$\delta R(h) = - \langle \text{Rc}, h \rangle - \Delta \text{tr}_g(h) + \text{div div } h.$$

It is not hard to see that since

$$\delta \log \det g = g^{ij} h_{ij}$$

so

$$\begin{aligned} \delta \sqrt{\det g} &= \delta \exp\left(\frac{1}{2} \log \det g\right) \\ &= \frac{1}{2} (\text{tr}_g h) \sqrt{\det g} \end{aligned}$$

so

$$\delta(dV) = \frac{1}{2} (\text{tr}_g h) dV.$$

Using the above formula we get

$$\begin{aligned} \delta(EH)(h) &= \int_M \left(- \langle \text{Rc}, h \rangle - \Delta \text{tr}_g(h) + \text{div div } h + \frac{1}{2} R (\text{tr}_g h) \right) dV \\ &= \int_M \left(- \langle \text{Rc}, h \rangle + \frac{1}{2} R (\text{tr}_g h) \right) dV \\ &= \int_M \left\langle \frac{1}{2} Rg - \text{Rc}, h \right\rangle dV. \end{aligned}$$

Remark 1 Here we used the divergence theorem for a compact Riemannian manifold, which says that

$$\int \langle \text{div } T, S \rangle dV = - \int \langle T, \nabla S \rangle dV,$$

for any n -tensor T and $(n-1)$ -tensor S . More explicitly,

$$\int g^{i_1 j_1} \dots g^{i_n j_n} g^{j_{i_0}} \nabla_j T_{i_0 i_1 \dots i_n} S_{j_1 j_2 \dots j_n} dV = \int g^{i_1 j_1} \dots g^{i_n j_n} g^{j_{i_0}} T_{i_0 i_1 \dots i_n} \nabla_j S_{j_1 j_2 \dots j_n} dV.$$

So critical points of the Einstein-Hilbert functional satisfy the Einstein equation. The gradient flow would be

$$\frac{\partial}{\partial t} g = -2 \left(\text{Rc} - \frac{1}{2} Rg \right).$$

The problem is that this flow is not parabolic and there is no existence theory for such equations.

Let's try a new tactic. Replace dV by a fixed measure dm . Then the functional

$$H(g) = \int_M R dm$$

satisfies the variation

$$\delta H(h) = \int_M \left(-\langle \text{Rc}, h \rangle - \Delta \text{tr}_g(h) + \text{div div } h \right) dm.$$

You don't lose the last two terms with the divergence theorem, since that only works with the volume measure. However, we can consider the Radon-Nikodym derivative and write

$$dm = \frac{dm}{dV} dV$$

for a positive function $\frac{dm}{dV}$. We can write

$$\frac{dm}{dV} = e^{-f}.$$

Then,

$$\delta H(h) = \int_M \left(-\langle \text{Rc}, h \rangle - \Delta \text{tr}_g(h) + \text{div div } h \right) e^{-f} dV$$

can be integrated by parts to get

$$\begin{aligned} \delta H(h) &= \int_M \left(-\langle \text{Rc}, h \rangle - \langle \nabla \text{tr}_g(h), \nabla f \rangle + \text{div } h \cdot \nabla f \right) e^{-f} dV \\ &= \int_M \left(-\langle \text{Rc}, h \rangle + \text{tr}_g(h) \Delta f - \text{tr}_g(h) |\nabla f|^2 - \langle h, \nabla^2 f \rangle + h(\nabla f, \nabla f) \right) e^{-f} dV \\ &= \int_M \left\langle -\text{Rc} - \nabla^2 f + \left(\Delta f - |\nabla f|^2 \right) g + \nabla f \nabla f, h \right\rangle e^{-f} dV. \end{aligned}$$

Remark 2 Tao often uses $\langle \cdot, \cdot \rangle$ to denote the Euclidean metric locally, and so explicitly puts in g^{ij} 's in this case. We will understand that $\langle \cdot, \cdot \rangle$ requires the metric, and so when quantities like this are differentiated, we also need to differentiate the metric, as we will see below.

We need to add another term, and so we get

$$F(g) = \int_M \left(R + |\nabla f|^2 \right) e^{-f} dV = \int_M \left(R + \left| \nabla \log \frac{dm}{dV} \right|^2 \right) dm.$$

We now need that

$$\begin{aligned} 0 &= \delta(dm) = \delta(e^{-f}dV) = -(\delta f)e^{-f}dV + \frac{1}{2}\text{tr}_g h e^{-f}dV \\ &= \left(-\delta f + \frac{1}{2}\text{tr}_g h\right)e^{-f}dV \end{aligned}$$

Thus we have that

$$\delta f = \frac{1}{2}\text{tr}_g h$$

Let

$$E(g) = \int (g^{ij}\nabla_i f \nabla_j f) e^{-f} dV$$

where $dm = e^{-f}dV$ is fixed (so that $f = -\log dm/dV$ and δf is expressed as above). We can then compute

$$\begin{aligned} \delta E(h) &= \delta \left[\int (g^{ij}\nabla_i f \nabla_j f) e^{-f} dV \right] \\ &= \int \left(-\langle h, \nabla f \nabla f \rangle + 2\langle \nabla f, \nabla(\delta f) \rangle - |\nabla f|^2 \delta f + \frac{1}{2} |\nabla f|^2 \text{tr}_g h \right) e^{-f} dV \\ &= \int \left(-\langle h, \nabla f \nabla f \rangle - 2\Delta f (\delta f) + |\nabla f|^2 \delta f + \frac{1}{2} |\nabla f|^2 \text{tr}_g h \right) e^{-f} dV \\ &= \int \left(\langle h, -\nabla f \nabla f - (\Delta f)g + |\nabla f|^2 g \rangle \right) e^{-f} dV. \end{aligned}$$

Now, since $F = H + E$, we have

$$\delta F(h) = \int_M \langle -\text{Rc} - \nabla^2 f, h \rangle e^{-f} dV.$$

Thus the gradient flow of $-2F$ is

$$\frac{\partial g}{\partial t} = -2\text{Rc}(g) - 2\nabla^2 f.$$

This is almost Ricci flow, but not quite. The f is changing, too, by the equation

$$\frac{\partial f}{\partial t} = -\Delta f - R.$$

This is a backward heat equation, which it turns out will make it useful to probe backwards.

Notice that

$$2\nabla^2 f = \mathcal{L}_{\nabla f} g,$$

the Lie derivative of g in the direction ∇f . This means that the flow above differs from Ricci flow by a diffeomorphism. Instead, we can consider $\bar{g} = \phi^* g$, where ϕ is the flow of diffeomorphisms generated by ∇f , and we will see that \bar{g} evolves by Ricci flow. Furthermore, f will differ by a Lie derivative, and

$$\mathcal{L}_{\nabla f} f = df(\nabla f) = |\nabla f|^2$$

(where is the metric in here? It is in ∇f , which is a vector field gotten by raising the index on df) and so under the new flow, $\bar{f} = f \circ \phi$ evolves by

$$\frac{\partial \bar{f}}{\partial t} = -\Delta_{\bar{g}} \bar{f} - \bar{R} + |\nabla \bar{f}|_{\bar{g}}^2.$$

Example 3 (Fundamental, important example) Let (M, g) be Euclidean space $M = \mathbb{R}^d$ and let

$$f(t, x) = \frac{|x|^2}{4\tau} + \frac{d}{2} \log 4\pi\tau = -\log \left[(4\pi\tau)^{-d/2} e^{-|x|^2/(4\tau)} \right]$$

where $\tau = t_0 - t$, Notice that $e^{-f} dx$ is the Gaussian measure, which solves the backward heat equation (the fundamental solution to the heat equation). If $t < t_0$, this choice of g and f satisfy the equations

$$\frac{\partial g}{\partial t} = -2 \text{Rc}(g) \tag{1}$$

$$\frac{\partial f}{\partial t} = -\Delta f - R + |\nabla f|^2. \tag{2}$$

We can check:

$$\begin{aligned} \frac{\partial f}{\partial t} &= \frac{\partial}{\partial t} \left[\frac{|x|^2}{4\tau} + \frac{d}{2} \log 4\pi\tau \right] \\ &= \frac{|x|^2}{4\tau^2} - \frac{d}{2\tau}. \end{aligned}$$

$$\nabla f = \frac{x}{2\tau}$$

$$|\nabla f|^2 = \frac{|x|^2}{4\tau^2}$$

$$\Delta f = \frac{d}{2\tau}$$

so it works.

Notice that when we pull back by ϕ , the measure $\phi^* dm$ is not static. Thus it makes sense to rewrite the functional as

$$F(M, g, f) = \int_M \left(R + |\nabla f|^2 \right) e^{-f} dV.$$

Notice that this functional is invariant under diffeomorphism, i.e.,

$$F(M, \phi^* g, f \circ \phi) = F(M, g, f)$$

for any diffeomorphisms ϕ . We also have that under the coupled flows (1) and (2),

$$\frac{\partial F}{\partial t}(M, g, f) = 2 \int |\text{Rc} + \nabla^2 f|^2 e^{-f} dV.$$

Thus we have that F is monotone increasing under Ricci flow. Unfortunately, now we have to explicitly deal with this quantity f . To eliminate this, we take the infimum:

$$\lambda(M, g) = \inf \left\{ F(M, g, f) : \int_M e^{-f} dV = 1 \right\}$$

(the infimum is over f). Using the following exercise, we can show that λ is finite.

Exercise 4 Show that $\lambda(M, g)$ is the smallest number for which one has the inequality

$$\int_M \left(4|\nabla u|_g^2 + Ru^2 \right) dV \geq \lambda \int_M u^2 dV,$$

where u is in $H^1(M) = W^{1,2}(M)$, the Sobolev space of functions with 1 derivative in L^2 (so it has norm $\|f\|_{H^1} = \left(\int (|\nabla f|_g^2 + f^2) dV \right)^{1/2}$ for C^1 functions). Hint: show that we can assume u is positive and then write $u = e^{-f/2}$. Thus λ is the smallest eigenvalue of the operator $-4\Delta_g u + R$.

Using the exercise, one sees that the fact that every compact manifold satisfies a Poincaré inequality,

$$\int_M |\nabla u|^2 dV \geq c(d) \int_M u^2 dV,$$

implies that λ is bounded below, basically, by the best constant in the Poincaré inequality plus $\min R$. Note that the Poincaré inequality constant depends on the dimension. We will see later a similar inequality for which the constant does not depend on dimension.

Furthermore, one can prove that λ is realized by a positive function $u = e^{-f/2}$ with $\|u\|_{L^2(M)} = 1$. Note that $H^1(M)$ embeds compactly into $L^2(M)$ since M is compact. Thus if we take a minimizing sequence $\{u_n\}$ in H^1 , there is a subsequence (which we also denote by $\{u_n\}$ which converges in L^2 to a function u . Now consider:

$$\begin{aligned} & \int (|\nabla u_n|^2 + Ru_n^2) dV + \int (|\nabla u_m|^2 + Ru_m^2) dV \\ &= \frac{1}{2} \int (|\nabla (u_n - u_m)|^2 + R(u_n - u_m)^2) dV + \frac{1}{2} \int (|\nabla (u_n + u_m)|^2 + R(u_n + u_m)^2) dV \end{aligned}$$

so

$$\begin{aligned} \frac{1}{2} \int (|\nabla (u_n - u_m)|^2 + R(u_n - u_m)^2) dV &= \int (|\nabla u_n|^2 + Ru_n^2) dV + \int (|\nabla u_m|^2 + Ru_m^2) dV \\ &\quad - \frac{1}{2} \int (|\nabla (u_n + u_m)|^2 + R(u_n + u_m)^2) dV. \end{aligned}$$

The right side goes to zero in the limit since the terms go to λ, λ and -2λ . Also, we know that

$$-\min |R| \|u_n - u_m\|_{L_2} \leq \int R (u_n - u_m)^2 dV \leq \min |R| \|u_n - u_m\|_{L_2}$$

and each term goes to zero. Thus we know that the sequence $\{u_n\}$ is Cauchy in H^1 and since H^1 is complete, it must converge to a function in H^1 .

Since λ is attained at a function, we can sometimes prove inequalities like the following (taken from the notes of Kleiner and Lott):

Let $h(s, t, x)$ be a two-parameter family of functions such that

$$\begin{aligned} h(s, t_0) &= f_*(t_0 + s) \\ \frac{\partial h}{\partial t} &= -\Delta h + -R + |\nabla h|^2. \end{aligned}$$

There is a solution to this for $t \leq t_0$ since the equation is backwards elliptic. (Note: we have only shown that f_* is in H^1 , so we mean a weak solution to the parabolic equation. We could also show that f_* , as a minimizer, satisfies a particular elliptic equation, which implies that f_* is smooth by elliptic regularity theory.)

$$\begin{aligned} \lambda(t_0) &\leq F(M, g(t_0), h(s, t_0 - s)) \\ &= F(M, g(t_0 + s), h(s, t_0)) - 2 \int_0^s \left[\int_M |\text{Rc}(g(t_0 + \sigma)) + \nabla^2 h(s, t_0 + \sigma)|^2 e^{-h(s, t_0 + \sigma)} dV \right] d\sigma. \end{aligned}$$

We then have

$$\lambda(t_0) \leq \lambda(t_0 + s) - 2 \int_0^s \left[\int_M |\text{Rc}(g(t_0 + \sigma)) + \nabla^2 h(s, t_0 + \sigma)|^2 e^{-h(s, t_0 + \sigma)} dV \right] d\sigma$$

and so

$$\begin{aligned} \frac{\partial \lambda}{\partial t}(t_0) &= \lim_{s \rightarrow 0^+} \frac{\lambda(t_0 + s) - \lambda(t_0)}{s} \\ &\geq \lim_{s \rightarrow 0^+} \frac{2}{s} \int_0^s \left[\int_M |\text{Rc}(g(t_0 + \sigma)) + \nabla^2 h(s, t_0 + \sigma)|^2 e^{-h(s, t_0 + \sigma)} dV \right] d\sigma \\ &= 2 \int_M |\text{Rc}(g(t_0)) + \nabla^2 h(0, t_0)|^2 e^{-h(0, t_0)} dV \\ &= 2 \int_M |\text{Rc}(g(t_0)) + \nabla^2 f_*(t_0)|^2 e^{-f_*} dV \end{aligned}$$

We can now derive

$$\begin{aligned}
\frac{\partial \lambda}{\partial t} &\geq 2 \int |\text{Rc} + \nabla^2 f_*|^2 e^{-f_*} dV \\
&\geq \frac{2}{3} \int (R + \Delta f_*)^2 e^{-f_*} dV \\
&\geq \frac{2}{3} \left[\int (R + \Delta f_*) e^{-f_*} dV \right]^2 \\
&= \frac{2}{3} \left[\int (R + |\nabla f_*|^2) e^{-f_*} dV \right]^2 \\
&= \frac{2}{3} \lambda^2.
\end{aligned}$$

3 Perelman entropy

We now wish to make our functional scale invariant (so that we get a critical quantity, not just subcritical). In particular, we know that

$$\frac{dF_m}{dt}(M, g) = 2 \int |\text{Rc} + \nabla^2 f|^2 e^{-f} dV$$

is fixed (under the gradient flow) if

$$\text{Rc} = -\nabla^2 f,$$

i.e., if (M, g) is a gradient Ricci soliton. We wish to have a new functional which is fixed if (M, g) is a gradient shrinking soliton, i.e.,

$$\text{Rc} = -\nabla^2 f + \frac{1}{2\tau} g$$

for some $\tau > 0$. A round sphere is a gradient shrinking soliton, so it makes sense that we would want something like this. Under the Ricci flow, this structure is preserved except that τ decreases at a constant rate.

First note that if we consider the Nash entropy

$$N_m(M, g) = \int_M \frac{dm}{dV} \log \frac{dm}{dV} dV = \int_M \left(\log \frac{dm}{dV} \right) dm = - \int f dm$$

then

$$\begin{aligned}
\frac{dN_m}{dt} &= - \int_M (-\Delta f - R) dm \\
&= \int_M (R + |\nabla f|^2) dm = F_m(M, g).
\end{aligned}$$

This will come in handy. Now, suppose we want a quantity $W(M, g)$ such that

$$\frac{dW}{dt} = \int_M \left| \text{Rc} + \nabla^2 f - \frac{1}{2\tau} g \right|^2 dm.$$

But in this case, would not have scale invariance for W , since t scales like distance squared, so the integrand should scale like distance squared. We will fix this by assuming

$$\frac{d\tau}{dt} = -1$$

and trying for

$$\frac{dW}{dt} = 2\tau \int_M \left| \text{Rc} + \nabla^2 f - \frac{1}{2\tau} g \right|^2 dm. \quad (3)$$

Now, to find such a quantity, consider

$$\left| \text{Rc} + \nabla^2 f - \frac{1}{2\tau} g \right|^2 = |\text{Rc} + \nabla^2 f|^2 - \frac{1}{\tau} (R + \Delta f) + \frac{d}{4\tau^2}.$$

Thus we have that

$$\begin{aligned} 2\tau \int_M \left| \text{Rc} + \nabla^2 f - \frac{1}{2\tau} g \right|^2 dm &= \tau \frac{dF_m}{dt} - 2F_m + \frac{d}{2\tau} \\ &= \frac{d}{dt} \left(\tau F_m - N_m - \frac{d}{2} \log \tau \right). \end{aligned}$$

This is what our W_m would be. However, as we did last time, we wanted to reparametrize so that

$$dm = e^{-f} dV$$

where dV is evolving according to Ricci flow evolution. This time, we will change

$$\tilde{f} = f - \frac{d}{2} \log(4\pi\tau)$$

so that

$$dm = e^{-f} dV = (4\pi\tau)^{-d/2} e^{-\tilde{f}} dV.$$

Remark 5 *This looks like the heat kernel for Euclidean space, which is why this particular normalization is given.*

Note that the preservation of dm implies that

$$\frac{d}{2\tau} - \frac{\partial \tilde{f}}{\partial t} + \frac{1}{2} \text{tr } h = 0.$$

Under the gradient flow

$$\frac{\partial g}{\partial t} = -2 \text{Rc} - 2 \nabla^2 f,$$

we have

$$\frac{\partial \tilde{f}}{\partial t} = \frac{d}{2\tau} - R - \Delta f.$$

Thus we get for

$$\begin{aligned} W_m(M, g, \tau) &= \tau F_m - N_m - \frac{d}{2} \log \tau \\ &= \int \left[\tau \left(R + |\nabla \tilde{f}|^2 \right) + \tilde{f} - \frac{d}{2} \log(4\pi) \right] (4\pi\tau)^{-d/2} e^{-\tilde{f}} dV \end{aligned}$$

Actually, we usually renormalize this to vanish in the Euclidean case, and so we can change the d term appropriately to

$$W_m(M, g, \tau) = \int \left[\tau \left(R + |\nabla \tilde{f}|^2 \right) + \tilde{f} - d \right] (4\pi\tau)^{-d/2} e^{-\tilde{f}} dV.$$

We can also define the Perelman entropy as the functional

$$W(M, g, f, \tau) = \int \left[\tau \left(R + |\nabla f|^2 \right) + f - d \right] (4\pi\tau)^{-d/2} e^{-f} dV$$

where g is a Riemannian metric, f is a function on M , and τ is a positive constant.

If g satisfies the Ricci flow, then we need to pull back f to get the three evolutions

$$\frac{\partial g}{\partial t} = -2 \text{Rc} \tag{4}$$

$$\frac{\partial f}{\partial t} = \frac{d}{2\tau} - R - \Delta f + |\nabla f|^2 \tag{5}$$

$$\frac{d\tau}{dt} = -1.$$

Under these three, the Perelman Entropy satisfies

$$\frac{dW}{dt}(M, g, f, \tau) = 2\tau \int_M \left| \text{Rc} + \nabla^2 f - \frac{1}{2\tau} g \right|^2 (4\pi\tau)^{-d/2} e^{-f} dV.$$

We would like to find a minimum over all functions f and constants τ so that we have an invariant of the Riemannian manifold. However, it is not yet clear that such an infimum exists. Recall that last time, the existence followed from a Poincaré inequality. In this scale invariant setting, the existence of a minimizer will follow from a log-Sobolev inequality.

4 Log-Sobolev inequalities

Let's first consider what happens if g is the Euclidean metric. We would like to switch to a function which looks like the heat kernel, namely,

$$u = (4\pi\tau)^{-d/2} e^{-f}.$$

Recall that our model case is when $f = |x|^2 / (4\tau)$, in which case this is precisely the backwards heat kernel. The backwards heat kernel satisfies:

$$\frac{\partial u}{\partial t} = -\Delta u$$

for $\tau > 0$ and

$$\lim_{\tau \rightarrow 0^-} u(\tau, x) = \delta_0(x),$$

weakly, where δ_0 is the delta function. Furthermore, one can check that

$$\int_{\mathbb{R}^d} u dx = \int_{\mathbb{R}^d} (4\pi\tau)^{-d/2} e^{-|x|^2/(4\tau)} dx = 1 \quad (6)$$

for any τ . The backwards heat kernel can be used to solve the heat equation with some given final conditions, e.g., to solve

$$\begin{aligned} \frac{du}{dt} &= -\Delta u \\ u(T, x) &= f(x), \end{aligned}$$

we see that the convolution

$$u(t, x) = \int_{\mathbb{R}^d} f(y) (4\pi\tau)^{-d/2} e^{-|x-y|^2/(4\tau)} dy$$

is a solution.

Exercise 6 Show that all of this is true. Hint: to show (6), turn the integral into polar coordinates and assume the dimension is at least 2. For the dimension 1 case, there is a trick involving turning it into a dimension 2 integral and separating.

We can check that for g Euclidean and f as above, we have

$$W(M, g, f, \tau) = \int \left[\frac{|x|^2}{2\tau} - d \right] (4\pi\tau)^{-d/2} e^{-|x|^2/(4\tau)} dx.$$

One can show that this is zero since

$$W(M, g, f, \tau) = \int \left[2\tau \left(|\nabla f|^2 - \Delta f \right) \right] (4\pi\tau)^{-d/2} e^{-f} dx,$$

and integrating by parts (needs to be justified) shows this is equal to zero.

Now we re-write W by replacing f with u . We see that (remembering still we are in Euclidean space),

$$W = \int \left[\tau \frac{|\nabla u|^2}{u^2} - u \log u \right] dx - \frac{d}{2} \log(4\pi\tau) - d$$

using identities such as

$$\begin{aligned} u &= (4\pi\tau)^{-d/2} e^{-f}. \\ \log u &= -\frac{d}{2} \log(4\pi\tau) - f \\ |\nabla u|^2 &= (4\pi\tau)^{-d} |\nabla f|^2 e^{-2f} \\ |\nabla f|^2 &= \frac{|\nabla u|^2}{u^2}. \end{aligned}$$

Tao shows that one can show that $W \geq 0$, which implies a log-Sobolev inequality

$$\tau \int \frac{|\nabla u|^2}{u^2} dx \geq \int u \log u dx + \frac{d}{2} \log(4\pi\tau) + d,$$

or as it is usually stated, with $\phi^2 = u$,

$$4\tau \int |\nabla \phi|^2 dx \geq \frac{1}{\tau} \int \phi^2 \log \phi^2 dx + \frac{d}{2} \log(4\pi\tau) + d.$$

For the general case, we have

$$W(M, g, f, \tau) = \int \left[\tau \left(Ru + \frac{|\nabla u|^2}{u^2} \right) - u \log u \right] dV - \frac{d}{2} \log(4\pi\tau) - d$$

One can show that the

$$W(M, g, f, \tau) \geq -C(M, g, \tau).$$

This implies essentially a log-Sobolev inequality, i.e.,

$$\tau \int R\phi^2 dV + \tau \int 4|\nabla \phi|^2 dV \geq -C + \int \phi^2 \log \phi^2 dV + \frac{d}{2} \log(4\pi\tau) + d.$$

In fact, we can take the

$$\mu(M, g, \tau) = \inf \left\{ W(M, g, f, \tau) : \int (4\pi\tau)^{-d/2} e^{-f} dV = 1 \right\},$$

which is the best possible constant $-C$. It can be shown that μ is finite, which is what we could call a log-Sobolev inequality.

We can now show that if $g(t)$ is a solution to Ricci flow on $t \in [0, T_0]$ and $\tau = T_0 - t$, then $\mu(M, g, \tau)$ is increasing. The first exercise is important:

Exercise 7 Show that $\mu(M, g, \tau) = W(M, g, f_*, \tau)$ for a function $f_* \in H^1(M)$. (Not quite true... What is the true statement? Hint: you need to change to a new function ϕ .)

Once we know that μ is realized by a function, we can show that $\mu(M, g(t), \tau(t))$ is increasing as follows. Calculate $\mu(M, g(t_0), \tau(t_0)) = W(M, g(t_0), f_*(t_0), \tau(t_0))$ for some minimizer $f_*(t_0)$. For any time $t \leq t_0$, we can solve the equation for f in 4 backwards to t with initial condition $f(t_0, x) = f_*(t_0, x)$ (since f_* is in $H^1(M)$, there exists a weak solution to this parabolic flow). We know that

$$\begin{aligned} \mu(M, g(t), \tau(t)) &\leq W(M, g(t), f(t), \tau(t)) \\ &\leq W(M, g(t_0), f_*(t_0), \tau(t_0)) = \mu(M, g(t_0), \tau(t_0)). \end{aligned}$$

5 Noncollapsing

We will now show that log-Sobolev inequalities imply noncollapsing. Suppose we have a ball $B(p, \sqrt{\tau})$ with bounded normalized curvature, i.e.,

$$|\text{Rm}(x)| \leq \frac{1}{\tau}$$

for $x \in B(p, \sqrt{\tau})$. Then $|R|\tau \leq c(d)$ for some constant depending only on dimension. Then the log-Sobolev inequality can be rewritten as

$$c(d) \int \phi^2 dV + \tau \int 4|\nabla\phi|^2 dV \geq \mu(M, g, \tau) + \int \phi^2 \log \phi^2 dV + \frac{d}{2} \log(4\pi\tau) + d.$$

Suppose ϕ is a function supported on $B(p, \sqrt{\tau})$ such that $\int_M \phi^2 dV = 1$. Then Jensen's inequality implies that

$$\begin{aligned} \frac{1}{V(B)} \int_B \phi^2 \log \phi^2 dV &\geq \left(\frac{1}{V(B)} \int_B \phi^2 dV \right) \log \left(\frac{1}{V(B)} \int_B \phi^2 dV \right) \\ &= \frac{1}{V(B)} \log \frac{1}{V(B)}, \end{aligned}$$

where $B = B(p, \sqrt{\tau})$. (Recall that Jensen's inequality requires a probability measure.) So

$$\int_M \phi^2 \log \phi^2 dV \geq \log \frac{1}{V(B)}.$$

We now get, for this particular choice of ϕ ,

$$4\tau \int |\nabla\phi|^2 dV \geq \mu(M, g, \tau) + \log \frac{\tau^{d/2}}{V(B)} - c'(d).$$

Now we will specialize ϕ even more. Suppose

$$\phi(x) = c\psi\left(\frac{d(x, p)}{\sqrt{\tau}}\right)$$

for some bump function ψ on the real line which is 1 on $[0, 1/2]$ and supported on $[0, 1]$ (technically, we only need half the bump function, which is how I described it). Thus $\phi(x) = c$ on $B(p, \sqrt{\tau}/2)$ and c is such that

$$\int_B \phi^2 dV = 1,$$

so $c \leq V(B(p, \sqrt{\tau}/2))^{-1/2}$. We can choose ϕ so that $|\nabla\phi| \leq c''c/\sqrt{\tau}$ on the ball (for some constant c''), and so

$$4c'' \frac{V(B)}{V(B_{1/2})} \geq \mu(M, g, \tau) + \log \frac{\tau^{d/2}}{V(B)} - c'(d).$$

Finally, we can use a Bishop-Gromov volume comparison theorem:

Theorem 8 (Bishop-Gromov comparison) *If (M^d, g) is a complete Riemannian manifold with*

$$\text{Rc} \geq (n-1)Kg$$

for some $K \in \mathbb{R}$, then for any $p \in M$, the volume ratio

$$\frac{V(B(p, r))}{V_K(B(p_K, r))}$$

is non-increasing as a function of r , where p_K is a point in the d -dimensional simply connected space of constant sectional curvature K , and $V_K(B(p_K, r))$ is the volume of a ball of radius r in that space.

In particular, we have that

$$\frac{V(B)}{V_{-1/\tau}(B(p_{-1/\tau}, \sqrt{\tau}))} \leq \frac{V(B_{1/2})}{V_{-1/\tau}(B(p_{-1/\tau}, \sqrt{\tau}/2))},$$

and thus there is a $\alpha = \alpha(\tau, d)$ such that

$$\frac{V(B)}{V(B_{1/2})} \leq \alpha.$$

In fact, α is independent of τ since

$$\begin{aligned} V_{-1/\tau}(B(p_{-1/\tau}, \sqrt{\tau})) &= V_{-1}(B(p_{-1}, 1)) \\ V_{-1/\tau}(B(p_{-1/\tau}, \sqrt{\tau}/2)) &= V_{-1}(B(p_{-1}, 1/2)). \end{aligned}$$

Thus there is a constant c''' which depends on d such that

$$c''' - \mu(M, g, \tau) \geq \log \frac{\tau^{d/2}}{V(B)},$$

i.e.,

$$V(B) \geq \left(e^{\mu - c'''}\right) \tau^{d/2},$$

which implies κ -noncollapsing at a scale $\sqrt{\tau}$ for $\kappa = \exp(\mu - c''')$. Let's formulate this into a proposition:

Proposition 9 *There is a constant $c = c(d)$ depending only on dimension such that if $\mu(M^d, g, \tau)$ is finite, then for $\kappa = \exp(\mu(M, g, \tau) - c)$, the Riemannian manifold (M, g) is κ -noncollapsed at the scale of $\sqrt{\tau}$.*

Let's collect the facts about μ .

Proposition 10 *The following are true about μ :*

1. $\mu(M, g, \tau) > -\infty$ for any fixed manifold (M, g) and $\tau > 0$.
2. If $(M, g(t))$ satisfies the Ricci flow for $t \in [0, T_0]$ and $\tau(t) = T_0 - t$, then $\mu(M, g(t), \tau(t))$ is increasing.
3. There is a constant $c = c(d)$ depending only on dimension such that the Riemannian manifold (M, g) is κ -noncollapsed at the scale of $\sqrt{\tau}$ at every point for $\kappa = \exp(\mu(M, g, \tau) - c)$.

We can now prove:

Theorem 11 (Perelman's noncollapsing theorem, first version) *Let $(M, g(t))$ be a solution to the Ricci flow on compact 3-manifolds for $t \in [0, T)$ such that at $t = 0$ we have*

$$\begin{aligned} |\text{Rm}(p)|_{g(0)} &\leq 1 \\ V(B_{g(0)}(p, 1)) &\geq \omega \end{aligned}$$

for all $p \in M$ and $\omega > 0$ fixed. For any $\rho > 0$, there exists $\kappa = \kappa(\omega, T, \rho) > 0$ such that the Ricci flow is κ -noncollapsed for all $(t_0, x_0) \in [0, T) \times M$ and scales $0 < r_0 < \rho$. We could also take $\rho = \rho(t)$ and get a similar result, as long as $\rho(t)$ is uniformly bounded on $[0, T)$.

Proof. We already showed that for a given τ and metric, $\mu(M, g, \tau)$ has a lower bound. For any r_0^2 , we see by monotonicity that

$$\mu(M, g(t), r_0^2) \geq \mu(M, g(0), r_0^2 + t).$$

Thus we have that if

$$\mu_0 = \inf \{ \mu(M, g(0), r^2) : r^2 \in (0, \rho + T) \}$$

then

$$\mu(M, g(t), r_0^2) \geq \mu_0.$$

Thus $(M, g(t))$ is κ -noncollapsed at the scale of r_0 for all

$$\kappa = \exp(\mu_0 - c) \leq \exp[\mu(M, g(t), r_0^2) - c].$$

We need to see that μ_0 is not $-\infty$. Since T is finite, there is no problem at the top of the interval for r^2 . It can be shown that as $r^2 \rightarrow 0^+$, $\mu(M, g(0), r^2) \rightarrow 0$ (in the interest of time, we will not show this) and so there is no problem at the other side. ■

Remark 12 *This is a bit stronger than what I proposed in an earlier lecture. I think Tao was thinking about future incarnations of this theorem, which is why he formulated as he did.*