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- The domain of the functions involved (usually denoted Ω) is an essential detail.
- Often other conditions placed on domain boundary, denoted $\partial \Omega$.



Jean-Baptiste le Rond d'Alembert





Pierre-Simon Laplace





Joseph Fourier

Pierre-Simon Laplace



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- PDEs have been around at least 250 years
- Co-evolved with physical sciences: mechanics, electromagnetism, quantum mechanics
- Modern uses are everywhere: chemistry, ecology, finance, image processing, big data

Name Wave equation Diffusion equation Laplace's equation Burger's equation Cahn-Hilliard equation Eikonal equation Fisher's equation Korteweg-de Vries eqn. Schrödinger eqn. Nonlinear Schrödinger eqn. Swift-Hohenberg eqn.

Equation $u_{tt} = c^2 u_{xx}$ $u_t = Du_{xx}$ $u_{xx} + u_{yy} = 0$ $u_t + uu_x = Du_{xx}$ $u_t = (u^3 - u - u_{xx})_{xx}$ $|\nabla u| = f(x)$ $u_{t} = u_{xx} + u(1-u)$ $u_{t} + 6uu_{x} + u_{xxx} = 0$ $iu_{t} + u_{yy} = 0$ $|u_t + u_{xx} + |u|^2 u = 0$ $u_t = -(\partial_{xx} + 1)^2 u + N(u)$ Application Vibrating string Heat flow Electrostatics etc. Fluid mechanics Phase separation Optics Ecology Water waves Quantum mech. Nonlinear optics Pattern formation

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If the domain is unbounded (e.g. Ω = ℝⁿ), useful to think of "boundary at infinity". *Far-field conditions* specify some kind of limiting behavior, e.g.

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If time is an independent variable, there can be initial conditions as with ODEs, e.g. requiring solution u(x, t) to satisfy u(x, 0) = g(x).

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- Uniqueness: there is only one solution.
- Stability: if the model changes a little, then the solution only changes a little.

Partial derivative notation

$$\frac{\partial}{\partial x}u(x,y)=\frac{d}{dx}\Big|_{y}u(x,y)=\partial_{x}u=u_{x}.$$

and multiple derivatives $\partial_x \partial_y u = u_{xy}$.

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 To actually compute integrals, sometimes go to coordinates and write as an iterated integral.