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- The domain of the functions involved (usually denoted $\Omega$ ) is an essential detail.
- Often other conditions placed on domain boundary, denoted $\partial \Omega$.

Jean-Baptiste le Rond d'Alembert


Joseph Fourier


Pierre-Simon Laplace


## History

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■ Co-evolved with physical sciences: mechanics, electromagnetism, quantum mechanics
■ Modern uses are everywhere: chemistry, ecology, finance, image processing, big data

## Some famous examples

Name
Wave equation
Diffusion equation
Laplace's equation
Burger's equation
Cahn-Hilliard equation
Eikonal equation
Fisher's equation
Korteweg-de Vries eqn.
Schrödinger eqn.
Nonlinear Schrödinger eqn.
Swift-Hohenberg eqn.

Equation
$u_{t t}=c^{2} u_{x x}$
$u_{t}=D u_{x x}$
$u_{x x}+u_{y y}=0$
$u_{t}+u u_{x}=D u_{x x}$
$u_{t}=\left(u^{3}-u-u_{x x}\right)_{x x}$
$|\nabla u|=f(x)$
$u_{t}=u_{x x}+u(1-u)$
$u_{t}+6 u u_{x}+u_{x x x}=0$
$i u_{t}+u_{x x}=0$
$i u_{t}+u_{x x}+|u|^{2} u=0$
$u_{t}=-\left(\partial_{x x}+1\right)^{2} u+N(u)$

Application
Vibrating string Heat flow
Electrostatics etc.
Fluid mechanics
Phase separation
Optics

## Ecology

Water waves
Quantum mech.
Nonlinear optics
Pattern formation

## Side conditions

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u(\mathbf{x})=f(\mathbf{x}), \quad \mathbf{x} \in \partial \Omega=\text { boundary of } \Omega
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Other common side conditions:

- If the domain is unbounded (e.g. $\Omega=\mathbb{R}^{n}$ ), useful to think of "boundary at infinity". Far-field conditions specify some kind of limiting behavior, e.g.

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- If time is an independent variable, there can be initial conditions as with ODEs, e.g. requiring solution $u(x, t)$ to satisfy $u(x, 0)=g(x)$.


## Well-posedness

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■ Existence: there is at least one solution to equation and side conditions. If this were not the case, the model may not tell us anything!

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- Stability: if the model changes a little, then the solution only changes a little.


## Notation of derivatives and integrals

- Partial derivative notation

$$
\frac{\partial}{\partial x} u(x, y)=\left.\frac{d}{d x}\right|_{y} u(x, y)=\partial_{x} u=u_{x}
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and multiple derivatives $\partial_{x} \partial_{y} u=u_{x y}$.

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- To actually compute integrals, sometimes go to coordinates and write as an iterated integral.

