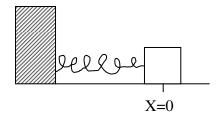
We start with:

$$m\ddot{x} + b\dot{x} + kx = 0$$
 m, b, $k > 0$ $\dot{x} = \frac{dx}{dt}$ and $\ddot{x} = \frac{dv}{dt}$

From physics we know F=ma and since $a = \ddot{x}$ this becomes F=m \ddot{x} and in a spring, which is the case we investigated, F=-kx



Looking at the homogeneous case of this would give us:

$$m\ddot{x} + kx = 0 \quad and \ x(t) = A\cos(\omega t + \varphi)$$
$$-\omega^2 A\cos(\omega t + \varphi) = -\frac{k}{m}A\cos(\omega t + \varphi)$$
$$\omega = \sqrt{\frac{k}{m}} \text{ and this is the Resonant frequency}$$

Now we go to the Non-homogeneous case.

$$m\ddot{x} + kx = F(t) = F_0 \cos(\omega t) but this time x(t) = B\cos(\omega t)$$

$$-\omega^2 mB\cos(\omega t) + kB\cos(\omega t) = F_0 \cos(\omega t)$$

$$B(-\omega^2 m + k) = F_0 \text{ the cosines cancel and B factors}$$

$$B = \frac{F_0}{-w^2 m + k} = \frac{F_0}{-w^2 m + k} = \frac{F_0}{Bm(\frac{k}{m} - w^2)} = \frac{F_0}{Bm(w_0^2 - w^2)}$$
Now looking at the graphs
$$k = \frac{x(t) = k\cos(\omega t + \varphi)}{w_0 - \omega}$$

$$k = \frac{w_0 - \omega}{w_0 - \omega}$$
Natural Frequency

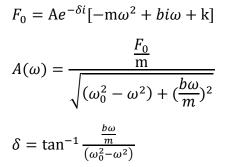
Now we look again at the equation

$$m\ddot{x} + kx = F(t) = F_0 \cos(\omega t) \text{ but this time } x(t) = Be^{\lambda t}$$
$$\lambda = \frac{-b \pm \sqrt{b^2 - 4(m)(k)}}{2m}$$

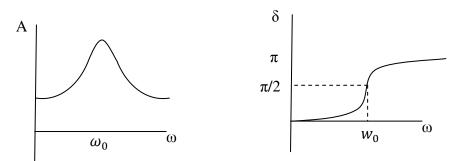
Look at the particular solution

 $z(t) = Ae^{i(\omega t - \delta)} \dot{z} = Ai\omega e^{i(\omega t - \delta)} \ddot{z}(t) = -A\omega^2 e^{i(\omega t - \delta)}$ We plug these back into the equation to get

 $-\mathbf{m}A\omega^2 e^{i(\omega t-\delta)} + bAi\omega e^{i(\omega t-\delta)} + \mathbf{k}Ae^{i(\omega t-\delta)} = F_0 e^{i\omega t}$ Simplifying gives us the equation



These are the graphs for the above 2 equations



This all can also be used for understanding of electrical concepts since mechanical and electrical have a very close correlation. Many terms can be related between the two.

Mechanical	Electrical
Force	Volts
Velocity	Current
Distance	Charge
μ	Resistance
k	Capacitor
Mass	L (Inductor)