Chapter 6: Laplace Transforms

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Definitions
Properties of the Laplace transform
Applications to ODEs and systems of ODEs

General properties

s-shifting, Laplace transform of derivatives & antiderivatives Heaviside and delta functions; t-shifting
Differentiation and integration of Laplace transforms

2. Properties of the Laplace transform

• The Laplace transform is a linear transformation, i.e. if f_1 and f_2 have Laplace transforms, and if α_1 and α_2 are constants, then

$$\mathcal{L}(\alpha_1 f_1 + \alpha_2 f_2) = \alpha_1 \mathcal{L}(f_1) + \alpha_2 \mathcal{L}(f_2).$$

As for Fourier transforms, the statement

$$f = \mathcal{L}^{-1}\left(\mathcal{L}(f)\right)$$

should be understood in a point-wise fashion only at points where f is continuous.

• Since there is no explicit formula for the inverse Laplace transform, formal inversion is accomplished by using tables, shifting t and s, taking derivatives of known Laplace transforms, or integrating them.

1. Definitions

• The Laplace transform, $\mathcal{L}(f)$, of a piecewise continuous function f (defined on $[0, \infty)$) is given by

$$\mathcal{L}(f)(s) = F(s) = \int_0^\infty \exp(-s t) f(t) dt.$$

• Clearly, the above integral only converges if f does not grow too fast at infinity. More precisely, if there exist constants M > 0 and $k \in \mathbb{R}$ such that

$$|f(t)| \leq M \exp(k t)$$

for t large enough, then the Laplace transform of f exists for all s > k.

• If f has a Laplace transform F, we also say that f is the inverse Laplace transform of F, and write $f = \mathcal{L}^{-1}(F)$.

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s-shifting, Laplace transform of derivatives & antiderivatives

- Note: All of the formulas written in what follows implicitly assume that the various functions used have well-defined Laplace transforms. One should therefore check that the corresponding Laplace transforms exist before using these formulas.
- s-shifting formulas

$$\mathcal{L}\left(e^{a\,t}f(t)\right)(s) = F(s-a), \qquad e^{a\,t}f(t) = \mathcal{L}^{-1}\left(F(s-a)\right)(t).$$

Laplace transform of derivatives

$$\mathcal{L}(f')(s) = s\mathcal{L}(f)(s) - f(0),$$

$$\mathcal{L}(f'')(s) = s^2\mathcal{L}(f)(s) - sf(0) - f'(0).$$

Laplace transform of derivatives and antiderivatives

More generally,

$$\mathcal{L}(f^{(n)})(s) = s^n \mathcal{L}(f)(s) - s^{n-1} f(0) - s^{n-2} f'(0) - \cdots - f^{(n-1)}(0).$$

• Laplace transform of antiderivatives

$$\mathcal{L}\left(\int_0^t f(\tau) \ d\tau\right)(s) = \frac{1}{s} \mathcal{L}(f)(s),$$

$$\int_0^t f(\tau) \ d\tau = \mathcal{L}^{-1}\left(\frac{1}{s} \mathcal{L}(f)(s)\right)(t).$$

- Examples:
 - Find the Laplace transforms of $sin(\omega t)$ and $cos(\omega t)$.
 - Find the inverse Laplace transforms of $1/(s(s^2+1))$ and $1/(s^2(s^2+1))$.

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Delta functions

• The Dirac delta function (or distribution) is defined as the limit of the following sequence of narrow top-hat functions,

$$\delta(t) = \lim_{\epsilon o 0} f_\epsilon(t), \qquad f_\epsilon(t) = \left\{ egin{array}{ll} rac{1}{2\epsilon} & ext{if } |t| \leq \epsilon \ 0 & ext{otherwise} \end{array}
ight.$$

- Since $\int_{-\infty}^{\infty} f_{\epsilon}(t) \ dt = 1$, we also write that $\int_{-\infty}^{\infty} \delta(t) \ dt = 1$.
- More generally, for a "well-behaved" function g, we have $\int_{-\infty}^{\infty} g(t) \; \delta(t-a) \; dt = g(a).$
- For a>0, this allows us to define the Laplace transform of $\delta(t-a)$ as

$$\mathcal{L}\left(\delta(t-a)\right)(s)=e^{-as}.$$

Heaviside and delta functions; t-shifting

• The Heaviside function (or step function) H(t) is defined as

$$H(t) = \left\{ egin{array}{ll} 0 & ext{if } t < 0 \ 1 & ext{if } t \geq 0 \end{array}
ight. .$$

- We can calculate that, for a > 0, $\mathcal{L}(H(t-a))(s) = \frac{e^{-as}}{s}$.
- More generally, we have the following time-shifting formulas for a > 0.

$$\mathcal{L}(f(t-a)H(t-a))(s) = e^{-as}\mathcal{L}(f)(s)$$

 $f(t-a)H(t-a) = \mathcal{L}^{-1}(e^{-as}\mathcal{L}(f)(s))(t).$

 The above formulas are useful to calculate the Laplace transforms of signals that are defined in a piecewise fashion.

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Differentiation and integration of Laplace transforms

In what follows, we write $\mathcal{L}(f)(s)$ as F(s).

• Differentiation of Laplace transforms

$$\mathcal{L}(tf(t))(s) = -F'(s),$$
 $\mathcal{L}^{-1}(F'(s))(t) = -tf(t).$

Integration of Laplace transforms

$$\mathcal{L}\left(\frac{f(t)}{t}\right)(s) = \int_{s}^{\infty} F(\nu) \ d\nu,$$

$$\mathcal{L}^{-1}\left(\int_{s}^{\infty} F(\nu) \ d\nu\right)(t) = \frac{f(t)}{t}.$$

• **Example:** Find the inverse Laplace transform of $s/(s^2+1)^2$.

Applications to ODEs and systems of ODEs

- Solve $y'' + y = t/\pi$, with $y(\pi) = 0$ and $y'(\pi) = 1 + 1/\pi$.
- Let $f(t)=\left\{ egin{array}{ll} rac{1}{2\epsilon} & \mbox{if } 1-\epsilon \leq t \leq 1+\epsilon \\ 0 & \mbox{otherwise} \end{array}
 ight.$, where $\epsilon < 1$. Solve y''+4y'-5y=f(t) with initial conditions y(0)=0 and y'(0)=0.
- Solve $y'' + 4y' 5y = \delta(t 1)$, with initial conditions y(0) = 0, y'(0) = 0.
- Solve the initial value problem $\frac{dX}{dt} = AX$,

$$A = \begin{bmatrix} -13 & -36 \\ 6 & 17 \end{bmatrix}, \qquad X(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$

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