

Multiple scales analysis of the van der Pol oscillator

```
> VDP:=diff(x(t),t,t)-epsilon*diff(x(t),t)*(1-x(t)^2)+omega[0]^2*x(t);
```

$$VDP := \left(\frac{d^2}{dt^2} x(t) \right) - \epsilon \left(\frac{d}{dt} x(t) \right) (1 - x(t)^2) + \omega_0^2 x(t)$$

≡ **Make the change of variable** $T = \Omega t$

```
> S1:=[T=Omega*t,x(t)=y(T)];
```

$$S1 := [T = \Omega t, x(t) = y(T)]$$

```
> VDP1:=convert(subs(t=solve(S1[1],t),subs(Omega=solve(S1[1],Omega),eval
(subs(subs(S1[1],S1[2]),VDP))))),diff);
```

$$VDP1 := \left(\frac{d^2}{dT^2} y(T) \right) \Omega^2 - \epsilon \left(\frac{d}{dT} y(T) \right) \Omega (1 - y(T)^2) + \omega_0^2 y(T)$$

≡ **Expand Ω and $y(t)$ in powers of ϵ and substitute in the differential equation**

```
> S2:=[Omega=omega[0]+epsilon*omega[1]+epsilon^2*omega[2],y(T)=y[0](T)+e
psilon*y[1](T)+epsilon^2*y[2](T)];
```

$$S2 := [\Omega = \omega_0 + \epsilon \omega_1 + \epsilon^2 \omega_2, y(T) = y_0(T) + \epsilon y_1(T) + \epsilon^2 y_2(T)]$$

```
> VDP2:=convert(series(subs(simplify(subs(S2,VDP1))),epsilon,3),diff);
```

$$\begin{aligned} VDP2 := & \left(\omega_0^2 y_0(T) + \left(\frac{d^2}{dT^2} y_0(T) \right) \omega_0^2 \right) + \left(- \left(\frac{d}{dT} y_0(T) \right) \omega_0 + \omega_0^2 y_1(T) + 2 \left(\frac{d^2}{dT^2} y_0(T) \right) \omega_0 \omega_1 \right. \\ & + \left. \left(\frac{d}{dT} y_0(T) \right) \omega_0 y_0(T)^2 + \left(\frac{d^2}{dT^2} y_1(T) \right) \omega_0^2 \right) \epsilon + \left(2 \left(\frac{d}{dT} y_0(T) \right) \omega_0 y_0(T) y_1(T) \right. \\ & - \left. \left(\frac{d}{dT} y_0(T) \right) \omega_1 + \left(\frac{d^2}{dT^2} y_0(T) \right) \omega_1^2 - \left(\frac{d}{dT} y_1(T) \right) \omega_0 + \left(\frac{d^2}{dT^2} y_2(T) \right) \omega_0^2 \right. \\ & + \left. 2 \left(\frac{d^2}{dT^2} y_1(T) \right) \omega_0 \omega_1 + \left(\frac{d}{dT} y_1(T) \right) \omega_0 y_0(T)^2 + 2 \left(\frac{d^2}{dT^2} y_0(T) \right) \omega_0 \omega_2 + \omega_0^2 y_2(T) \right. \\ & \left. + \left(\frac{d}{dT} y_0(T) \right) \omega_1 y_0(T)^2 \right) \epsilon^2 + O(\epsilon^3) \end{aligned}$$

Note that the above equation is only valid up to order ϵ^2 since the expansions for ω and $y(T)$ were truncated at order 3.

≡ **Solve the differential equations obtained at each order**

Order ε^0

```
> VDP0:=convert(subs(epsilon=0,VDP2),diff);
```

$$VDP0 := \omega_0^2 y_0(T) + \left(\frac{d^2}{dT^2} y_0(T) \right) \omega_0^2$$

```
> E1:=y[0](T)=A*cos(T+phi);
```

$$E1 := y_0(T) = A \cos(T + \varphi)$$

```
> simplify(eval(subs(E1,VDP0)));
```

0

Order ε

```
> coeff(VDP2,epsilon);
```

$$-\left(\frac{d}{dT} y_0(T) \right) \omega_0 + \omega_0^2 y_1(T) + 2 \left(\frac{d^2}{dT^2} y_0(T) \right) \omega_0 \omega_1 + \left(\frac{d}{dT} y_0(T) \right) \omega_0 y_0(T)^2 + \left(\frac{d^2}{dT^2} y_1(T) \right) \omega_0^2$$

Substitute solution at order ε^0

```
> E2:=convert(collect(simplify(eval(subs(E1,coeff(VDP2,epsilon)))),
[diff(y[1](T),T,T),y[1](T)]),diff);
```

$$E2 := \left(\frac{d^2}{dT^2} y_1(T) \right) \omega_0^2 + \omega_0^2 y_1(T) - \omega_0 (-A \sin(T + \varphi) + 2 A \cos(T + \varphi) \omega_1 + A^3 \sin(T + \varphi) \cos(T + \varphi)^2)$$

Solve for $y_1(t)$

```
> E3:=collect(simplify(subs(_C1=0,_C2=0,dsolve(E2,y[1](T))),T,combine);
```

$$E3 := y_1(T) = \frac{\left(\frac{1}{2} A \cos(T + \varphi) + A \sin(T + \varphi) \omega_1 - \frac{1}{8} A^3 \cos(T + \varphi) \right) T}{\omega_0} + \frac{-8 A \sin(T + \varphi) + 16 A \cos(T + \varphi) \omega_1 - A^3 \sin(3 T + 3 \varphi) + 2 A^3 \sin(T + \varphi)}{32 \omega_0}$$

Note that $y_1(T)$ diverges, unless the term proportional to T is zero. This gives us a **solvability condition** for the differential equation for $y_1(T)$

Solvability condition

```
> E4:=collect(A*omega[1]*sin(T+phi)+1/2*A*cos(T+phi)-1/8*A^3*cos(T+phi),[cos(T+phi),sin(T+phi)])=0;
```

$$E4 := \left(\frac{1}{2} A - \frac{1}{8} A^3 \right) \cos(T + \varphi) + A \sin(T + \varphi) \omega_1 = 0$$

Find the values of A and ω_1 which satisfy the solvability condition

```
> E5:={coeff(op(1,E4),cos(T+phi))=0,coeff(op(1,E4),sin(T+phi))=0};
```

$$E5 := \left\{ A \omega_1 = 0, \frac{1}{2} A - \frac{1}{8} A^3 = 0 \right\}$$

```
> solve(E5, {A, omega[1]});
```

$$\{A = 0, \omega_1 = \omega_1\}, \{A = 2, \omega_1 = 0\}, \{A = -2, \omega_1 = 0\}$$

From now on, we set $A = 2$ and $\omega_1 = 0$.

Re-write the solutions obtained at orders ε^0 and ε

```
> E6 := [subs(A=2, E1), subs(A=2, collect(subs(omega[1]=0, E3), [cos(T+phi), sin(T+phi)])), omega[1]=0];
```

$$E6 := \left[y_0(T) = 2 \cos(T + \varphi), y_1(T) = -\frac{\sin(3T + 3\varphi)}{4\omega_0}, \omega_1 = 0 \right]$$

Order ε^2

Equation for $y_2(T)$

```
> E7 := simplify(eval(subs(E6, coeff(VDP2, epsilon^2))));
```

$$E7 := 2 \sin(T + \varphi) \cos(T + \varphi) \sin(3T + 3\varphi) + \frac{3}{4} \cos(3T + 3\varphi) + \left(\frac{d^2}{dT^2} y_2(T) \right) \omega_0^2 - 3 \cos(3T + 3\varphi) \cos(T + \varphi)^2 - 4 \cos(T + \varphi) \omega_0 \omega_2 + \omega_0^2 y_2(T)$$

Solution. Note the secular terms in T

```
> E8 := collect(subs(_C1=0, _C2=0, dsolve(E7, y[2](T))), T, combine);
```

$$E8 := y_2(T) = \frac{(16 \sin(T + \varphi) \omega_0 \omega_2 + \sin(T + \varphi)) T}{8 \omega_0^2} + \frac{96 \cos(T + \varphi) \omega_0 \omega_2 + 6 \cos(T + \varphi) - 5 \cos(5T + 5\varphi) - 9 \cos(3T + 3\varphi)}{96 \omega_0^2}$$

Solvability conditions - set the term in T to 0 and solve for ω_2

```
> E9 := 1/8 * (16 * sin(T+phi) * omega[0] * omega[2] + sin(T+phi)) / omega[0]^2 = 0;
```

$$E9 := \frac{16 \sin(T + \varphi) \omega_0 \omega_2 + \sin(T + \varphi)}{8 \omega_0^2} = 0$$

```
> E10 := omega[2] = solve(E9, omega[2]);
```

$$\omega_2 = -\frac{1}{16 \omega_0}$$